IN THE CLAIMS:

Listing of Claims:

1   **Claim 1.**   (currently amended) An emitter locator system, comprising:

2   a mobile DF set, said set comprising a receiver for receiving incident signal
3   transmissions;

4   a line of bearing (LOB) generating system in operative communication with said
5   receiver and configured to generate lines of bearing responsive to said received signal
6   transmissions;

7   an LOB error generating system in operative communication with said line of
8   bearing generating system and configured to generate error boundsfactors related to said
9   lines of bearing, said line of bearing generating system and said LOB error generating
10   system executed by a computing device, said computing device operatively generating a
11   cross-over point, said cross-over point defined as the intersection of a pair of sequential
12   real-time lines of bearing from said mobile DF set, each said line of bearing
13   corresponding to a wireless transmission from said transmitter received by said mobile
14   DF set and said computing device then estimates a future position of said transmitter in
15   reference to said cross-over point;

16   an probability overlay generating system in operative communication with said
17   LOB error generating system and configured to generate an overlay probability map
18   responsive to said error boundsfactors; and

19   display means for visually displaying said lines of bearing, said error
20   boundsfactors and said overlay map.

1   **Claim 2.**   (currently amended) The system of Claim 1, wherein:

2   said incident signal transmissions are further defined by strength and clarity
3   factors;

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4   said line of bearing generating system further generates quality numbers for each

5   said line of bearing responsive to said strength and clarity factors; and

6   said LOB error generating system generates said error ~~bounds~~factors responsive

7   to said quality numbers.

1   **Claim 3.** (currently amended) The system of Claim 2, further comprising a second DF

2   set in communication with said mobile DF set, said second set comprising a receiver for

3   receiving incidental signal transmissions, the system further comprising:

4   said line of bearing generating system;

5   said LOB error generating system;

6   said probability overlay generating system; and

7   said display means for further visually displaying said lines of bearing, said error

8   ~~bounds~~factors and said overlay map, said lines of bearing generated by said mobile DF

9   set and said second DF set.

1   **Claim 4.** (original) The system of Claim 3, wherein said display means of said mobile

2   DF set further displays said lines of bearing generated by said second DF set.

1   **Claim 5.** (original) The system of Claim 2, wherein said mobile DF set further

2   comprises a position estimating system for determining the spacial location of said

3   transmitter responsive to said lines of bearing and said LOB errors.

1   **Claim 6.** (original) The system of Claim 5, wherein said display means further displays

2   said spacial location of said transmitter.

1   **Claim 7.** (original) The system of Claim 6, wherein said probability overlay generating

2   system is further responsive to said spacial location of said transmitter.

1   **Claim 8.** (original) The system of Claim 7, wherein said probability overlays comprise

2   a two-dimensional composite of concentric shapes.

1   **Claim 9.** (currently amended) The system of Claim 8, wherein said concentric shapes

2   comprise an inner shape concentric to an outer shape, said inner shape configuration

3   representative of said error ~~bounds~~factors having relatively small values and said outer

4   shape configuration representative of said error ~~bounds~~factors having relatively large

5   values.

1   **Claim 10.** (currently amended) A direction-finding method comprising the steps of:

2   establishing a cross-over position point;

3   relocating a receiver to a new receiver spacial location;

4   said receiver at said new receiver position receiving a transmission from a

5   transmitter at a transmitter position;

6   determining a real-time line of bearing from said receiver to said transmitter;

7   generating a connecting vector from said real-time line of bearing to said cross-

8   over position point; and

9   identifying a real-time position of said transmitter along said connecting vector;

10   displaying said real-time position on a user display panel; and

11   generating and displaying an probability overlay map responsive to said real-time

12 position and ~~a~~said quality factor on said user display panel.

1   **Claim 11.** (original) The method of Claim 10, wherein said identifying step further

2   comprises assigning a probability factor to said real-time position of said transmitter

3   responsive to said quality factor and said probability overlay map generating and

4   displaying is responsive to said probability factor.

1   **Claim 12.** (original) The method of Claim 11, further comprising a repeating step to

2   repeat said relocating, receiving, determining, generating, identifying, displaying and

3   generating steps until said probability factor exceeds a predetermined threshold value.

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1 **Claim 13.** (original) The method of Claim 11, further comprising a repeating step to
2 repeat said relocating, receiving, determining, generating, identifying, displaying and
3 generating steps until said probability factor meets a user-defined threshold value.

1 **Claim 14.** (original) The method of Claim 11, further comprising a repeating step to
2 repeat said relocating, receiving, determining, generating, identifying, displaying and
3 generating steps until a user terminates said direction finding method.

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